

# Integrated Imaging And Communication with Reconfigurable Intelligent Surfaces

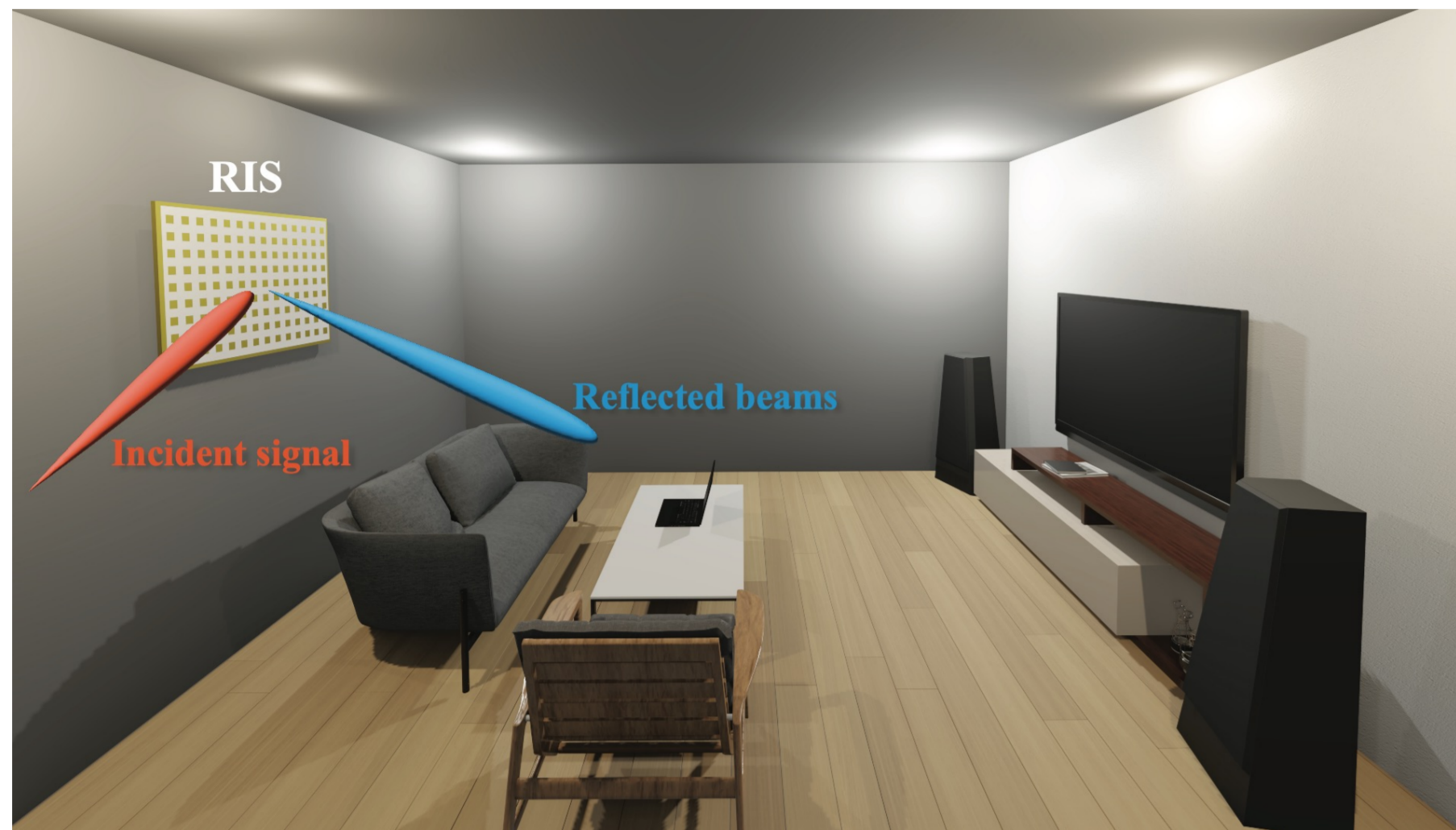
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## RIS Beam Training is a Key Challenge

Large numbers of antennas

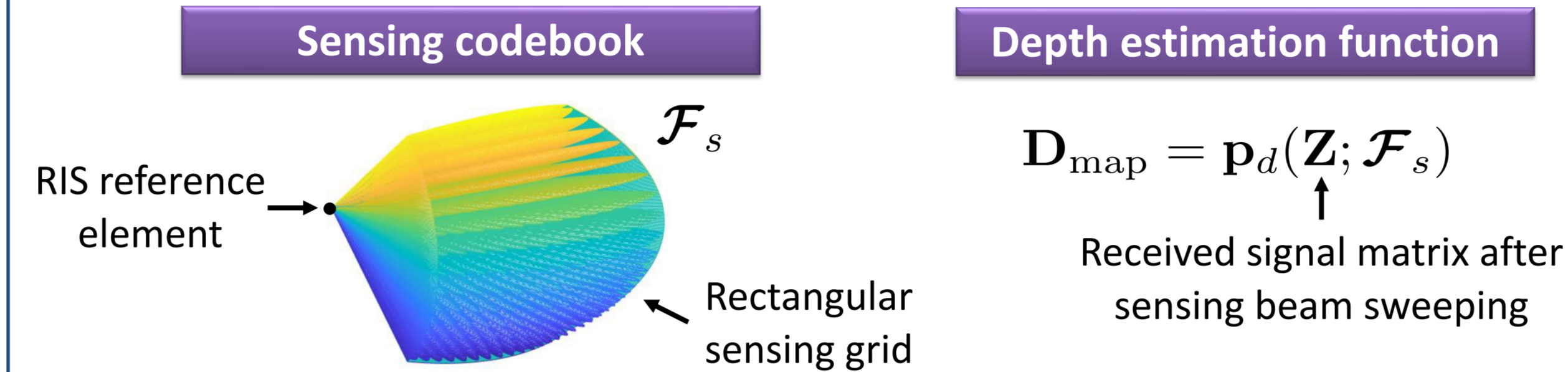
Narrow beams



- RIS offers an opportunity for high spatial-resolution imaging
- Can imaging assist RIS beam training for communication?

## Problem Formulation

### ➤ RIS-aided depth estimation



[Taha'23] A. Taha, H. Luo, and A. Alkhateeb, "Reconfigurable Intelligent Surface Aided Wireless Sensing for Scene Depth Estimation," in IEEE ICC, 2023.

### ➤ RIS beam selection problem with a predefined codebook

User detection function

$$(\tilde{\theta}_{UE}^{az}, \tilde{\theta}_{UE}^{ze}) = \mathbf{p}_u(\mathbf{D}_{\text{map}})$$

Optimal beam index

$$m^* = \arg \max_{\psi_m^c \in \mathcal{F}_c} |(\mathbf{h}_R \odot \mathbf{h}_T)^T \psi_m^c|$$

### ➤ Objective: Find the optimal beam based on user detection

## RIS Beam Selection

### ➤ Decomposition of RIS interaction vector

$$\tilde{\psi}^c = \tilde{\psi}_{AP}^c \odot \tilde{\psi}_{UE}^c$$

Far-field array response vector

$$\tilde{\psi}_{AP}^c = \mathbf{a}^*(\theta_{AP})$$

Angles towards the AP (known)

$$\tilde{\psi}_{UE}^c = \mathbf{a}^*(\theta_{UE})$$

Angles towards the user

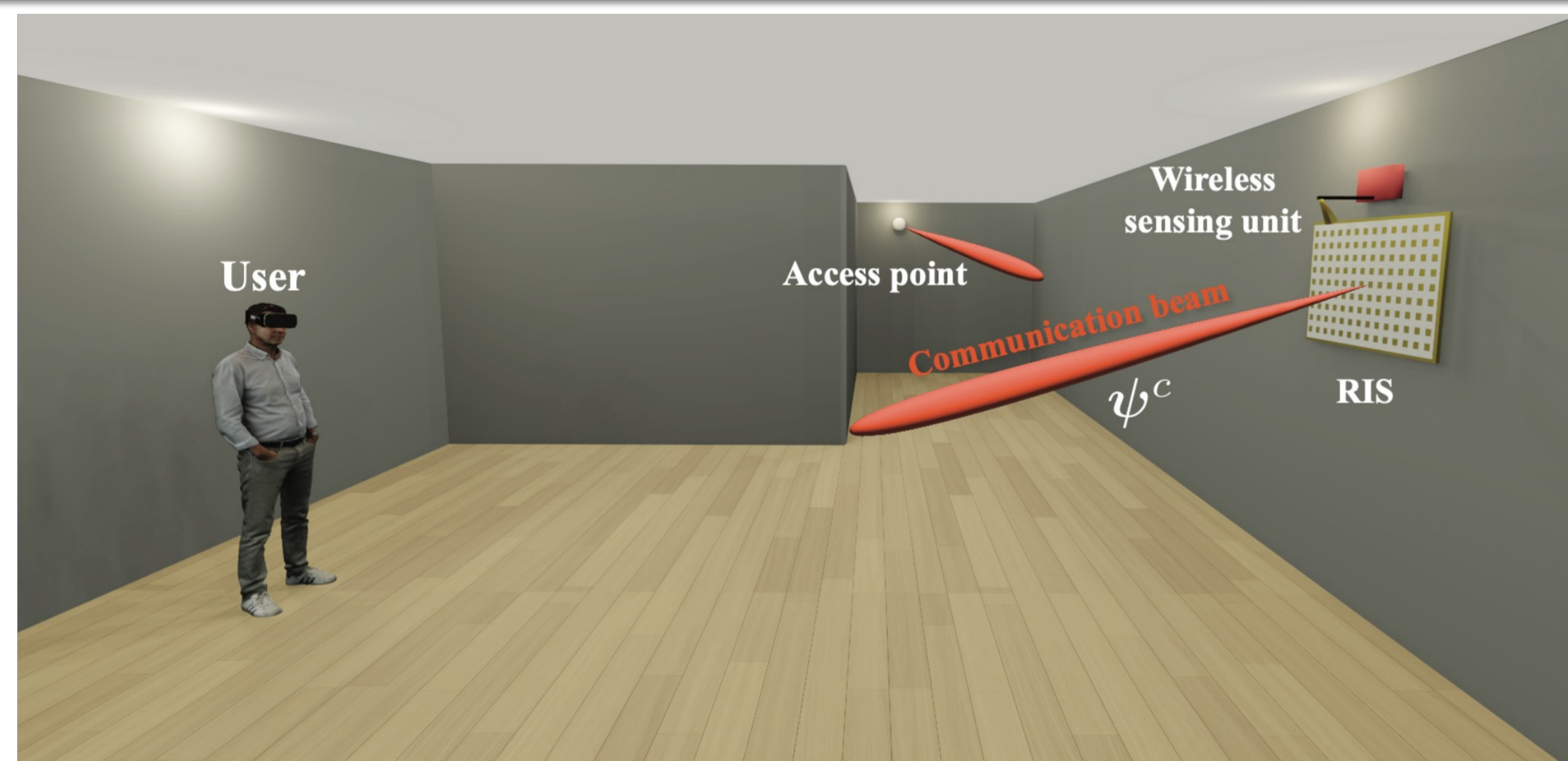
### ➤ Similarities between estimated beam and codebook beams

$$\tilde{m} = \arg \max_{\psi_m^c \in \mathcal{F}_c} |(\tilde{\psi}^c)^H \psi_m^c|$$

- Note: A set of candidate beams can be found by sorting the codebook based on the calculated similarities

## System Model

### ➤ Communication model



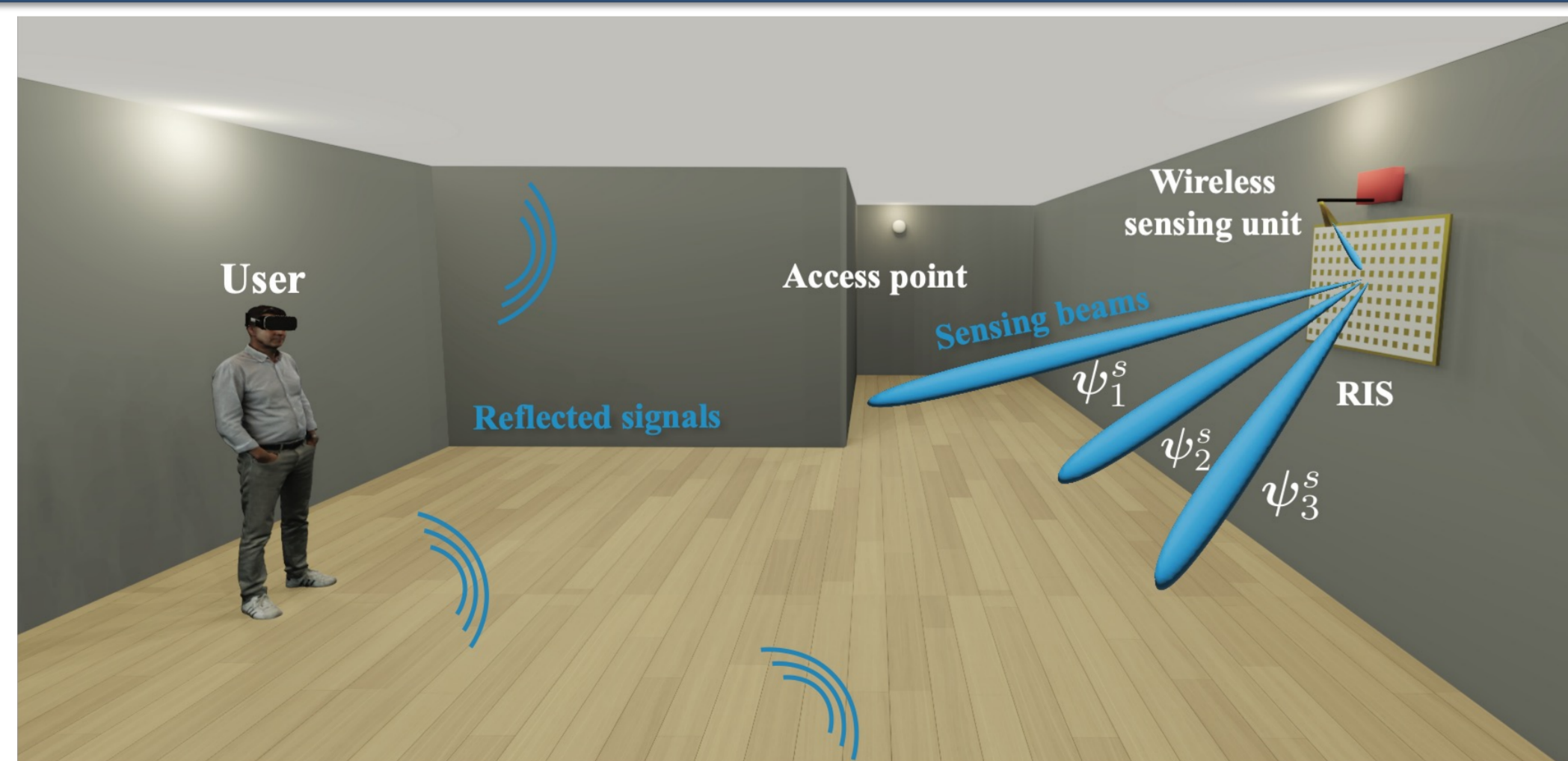
$$y_c = (\mathbf{h}_R \odot \mathbf{h}_T)^T \psi^c x_c + w_c$$

Received signal

RIS interaction vector for communication

RIS-UE channel AP-RIS channel

### ➤ Imaging model (based on beamformed FMCW)



$$z[u, v] = \sum_{k=1}^K \sum_{\ell=1}^{L_k} \sqrt{\rho_{k,\ell}} e^{-j\theta_{k,\ell}} e^{+j\Xi_{k,\ell}} + w_s[u, v] e^{j\chi[u]}$$

Received baseband digital signal

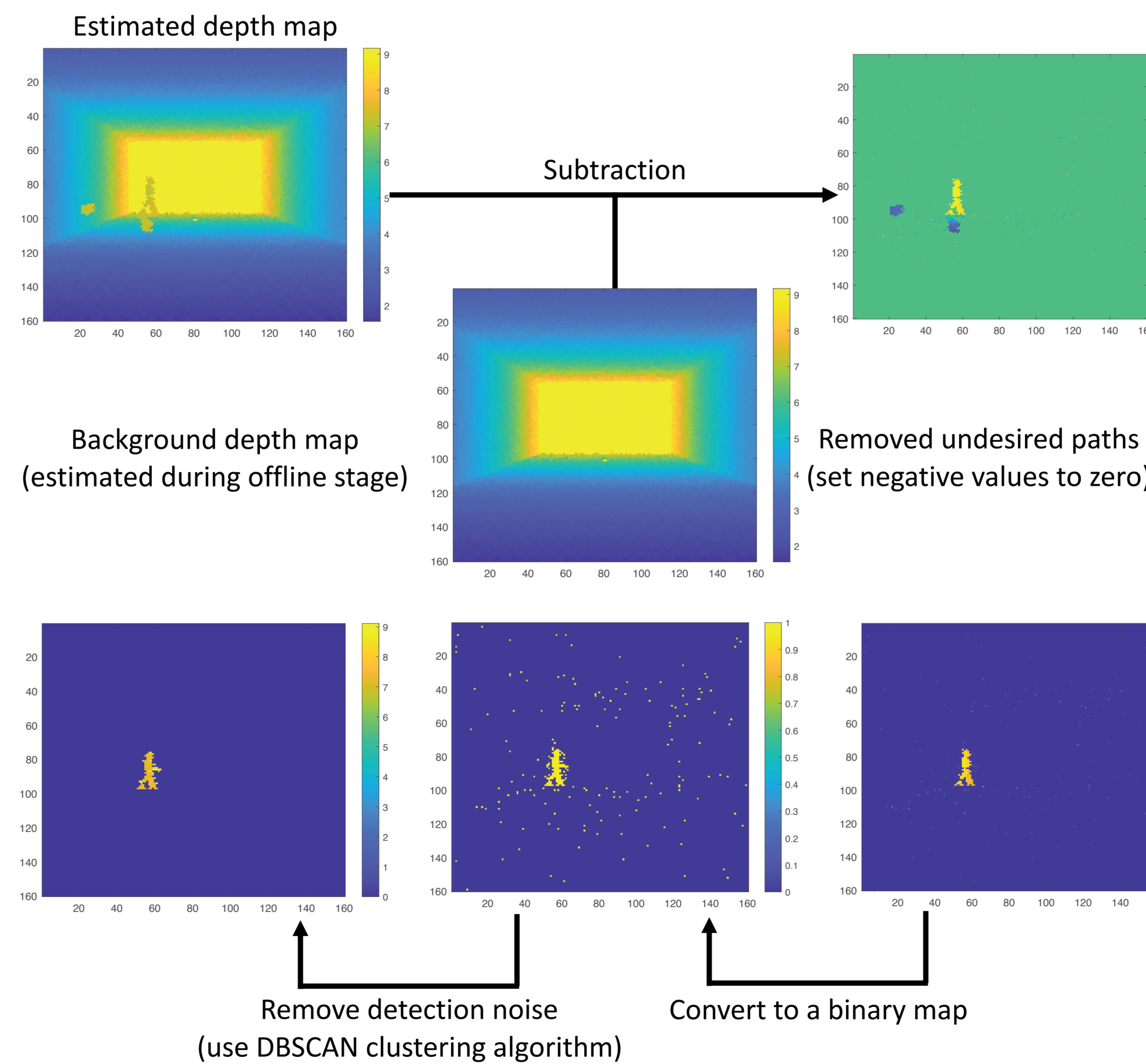
$u^{\text{th}}$  ADC sample

$v^{\text{th}}$  sensing beam (chirp)

Path gain and phase

Contain range information

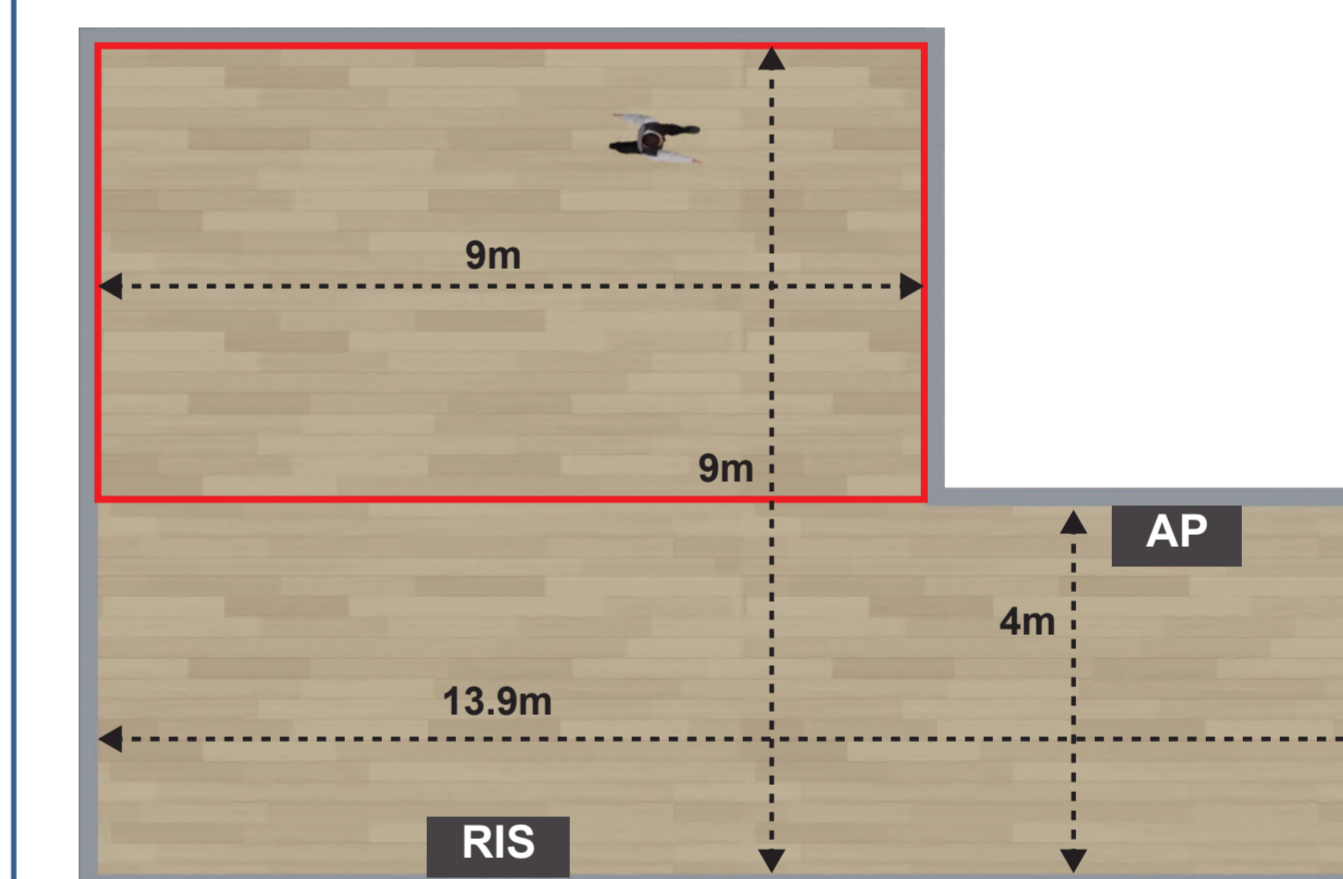
## User Detection in RIS-based Depth Map



- To determine the azimuth and zenith angles towards the user
  - Find the mean of the user's pixel coordinates
  - Each pixel is estimated by a sensing beam of a predefined reflected direction

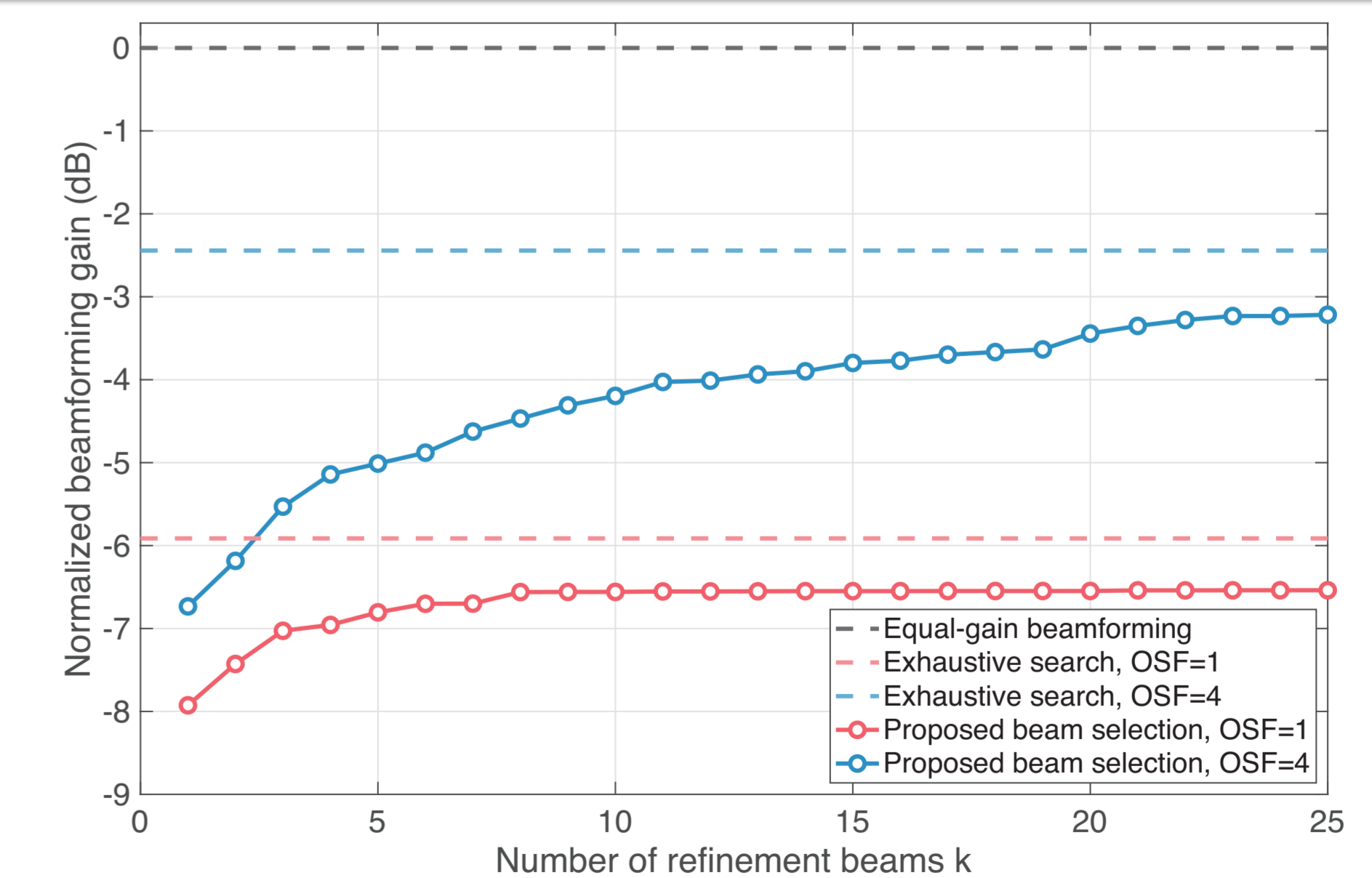
## Simulation Results

### ➤ Simulation framework



- RIS structure: 40x40 UPA
- Operating band: 60 GHz
- Comm. codebook: Beamsteering
- Floor plan design: Blender
- Ray-tracing simulator: Wireless Insite
- User is in the NLoS area (red box)

### ➤ Results



Note: Normalized beamforming gain is the ratio of beamforming gain to equal-gain beamforming gain

- Oversampled codebook provides better beamforming gain
- With oversampling factors of four in azimuth and zenith
  - Achieve comparable performance to the exhaustive search
  - Require 1000 times less beam training overhead